

Semi-discrete equations in Banach spaces: The approximate inverse approach

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Wave
phenomena

AI in Banach spaces: pros and cons

Pros:

- No geometric assumptions on Banach spaces.
- Discretization effects included into the analysis.

Cons:

- Some components may not be easily available in concrete applications.
- Abstract concept; not easily presented.

Setting the stage

- X, Y real Banach spaces
- $A \in \mathcal{L}(X, Y)$, $R(A) \neq \overline{R(A)}$

inverse problem: $Af = g$ where $g \in R(A)$

Remarks:

- ▶ The inverse problem is ill-posed in the sense of Nashed.
- ▶ There is no bounded inner inverse for A :

$$\nexists B \in \mathcal{L}(Y, X): ABA = A.$$

Inner inverses are equation solvers: $\tilde{f} = Bg$ solves the inverse problem.

- ▶ In the Hilbert space setting A^+ (Moore-Penrose inverse) is an inner inverse which is bounded iff $R(A) = \overline{R(A)}$.

Modelling including Measurement Process

$\Psi_n: Y \rightarrow \mathbb{R}^n$ observation operator (linear, bounded)

Example: $\psi_i \in Y'$ sensitivity profile of i -th detector

$$\Psi_n g := (\langle \psi_1, g \rangle_{Y' \times Y}, \dots, \langle \psi_n, g \rangle_{Y' \times Y})^\top$$

Semi-discrete problem (SDP): $A_n f_n = g_n$ (No discretization!)

where

$$A_n = \Psi_n A \in \mathcal{L}(X, \mathbb{R}^n), \quad g_n = \Psi_n g, \quad f_n \in X$$

- ▶ SDP is highly under-determined!
- ▶ If X is uniformly convex then the minimum norm solution of SDP is well defined and unique.

The key concept: computing moments

- ▶ Instead of trying to find a solution $f_n \in X$ of SDP we aim at computing moments:

$$\langle e_{d,i}, f_n \rangle_{X' \times X} \quad \text{for mollifiers } e_{d,i} \in X', \quad i = 1, \dots, d.$$

- ▶ Then, we recover an approximate solution $E_d f_n$ of SDP by

$$E_d f_n := \sum_{i=1}^d \langle e_{d,i}, f_n \rangle_{X' \times X} b_{d,i}$$

where $\{b_{d,i}\}_{i=1}^d \subset X$.

- ▶ $\{e_{d,i}\}_{i=1}^d \subset X'$ and $\{b_{d,i}\}_{i=1}^d \subset X$ have to be intertwined such that E_d satisfies the *mollifier property*

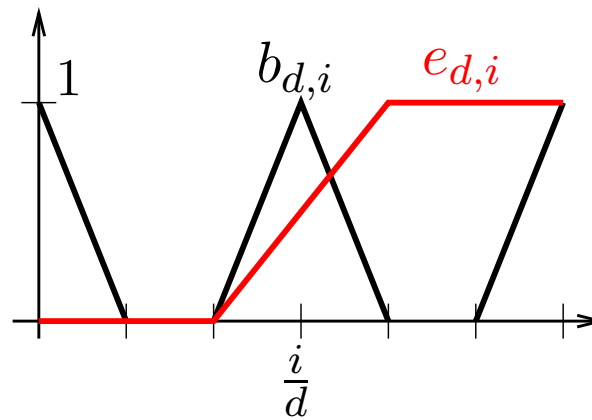
$$\lim_{d \rightarrow \infty} \|E_d w - w\|_X = 0 \quad \text{for any } w \in X.$$

Mollifier property: an example

► $X = (\mathcal{C}([0, 1]), \|\cdot\|_\infty)$, $X' \simeq \text{BV}_*(0, 1)$: $f \mapsto \langle \mu, f \rangle_{X' \times X} := \int_0^1 f(x) d\mu(x)$.

► Define

$$E_d f = \sum_{i=0}^d \langle e_{d,i}, f \rangle_{X' \times X} b_{d,i} \quad \text{where} \quad \langle e_{d,i}, f \rangle_{X' \times X} = \frac{2}{d} \int_{(i-1)/d}^{(i+1)/d} f(x) dx.$$



Then,

$$\lim_{d \rightarrow \infty} \|f - E_d f\|_\infty = 0 \quad \text{for any } f \in \mathcal{C}(0, 1).$$

Moreover, $\|f - E_d f\|_\infty \leq C_E d^{-\alpha} \|f\|_{\mathcal{C}^\alpha(0,1)}$, $0 < \alpha \leq 1$.

Reconstruction kernels: the basic idea

To evaluate $E_d f_n$ we need to calculate the moments $\langle e_{d,i}, f_n \rangle_{X' \times X}$.

Let the equations

$$A_n^* v_{d,i}^n = e_{d,i}, \quad i = 1, \dots, d, \quad (1)$$

have solutions. Then,

$$\langle e_{d,i}, f_n \rangle_{X' \times X} = \langle v_{d,i}^n, A_n f_n \rangle_2 = \langle v_{d,i}^n, g_n \rangle_2$$

and defining

$$\tilde{A}_{n,d}: \mathbb{R}^n \rightarrow X, \quad \tilde{A}_{n,d} \alpha := \sum_{i=1}^d \langle v_{d,i}^n, \alpha \rangle_2 b_{d,i}$$

we obtain

$$\tilde{A}_{n,d} A_n = E_d.$$

► $\tilde{A}_{n,d}$ *approximate inverse* of A_n , $v_{d,i}^n$ *reconstruction kernel*

However, (1) cannot be expected to have solutions.

(LOUIS, MAASS 1990, LOUIS 1996)

Surrogate kernels from the underlying continuous setting

Let A be injective. Given $\varepsilon > 0$ and $e \in X'$.

- ▶ If X is reflexive, $\mathcal{R}(A^*)$ is dense in X' and we find $v \in Y$:

$$\|A^*v - e\|_{X'} \leq \varepsilon$$

- ▶ If X is arbitrary, $\mathcal{R}(A^*)$ is weak* dense in X' .

Let $f \in X$ denote the (unique) solution of $Af = g$.

Then, we find $v = v(f) \in Y$

$$|\langle A^*v - e, f \rangle_{X' \times X}| \leq \varepsilon \|f\|_X.$$

We call v a continuous kernel with inaccuracy ε (related to A , f , and e).

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Continuous kernels: an example

▶ $X = (\mathcal{C}([0, 1]), \|\cdot\|_\infty)$, $X' \simeq \text{BV}_*(0, 1)$

▶ $A: X \rightarrow X$, $Af(x) = \int_0^x f(t)dt$

▶ $A^*: X' \rightarrow X'$, $A^*\mu(\xi) = \mu(1)\xi - A\mu(\xi)$.

▶ Let $\eta \in X'$ with $\int_0^1 \eta(t)dt = 1$ and $\eta(1) = 0$. Define $e(x) := A\eta(x)$.

Then, $v(x) = -\eta(x)$ satisfies

$$A^*v(\xi) = v(1)\xi - Av(\xi) = -\eta(1)\xi + A\eta(\xi) = e(\xi).$$

▶ Let $\eta_\gamma = \chi_{[z-\gamma, z+\gamma[} / (2\gamma)$ for a fixed $z \in]0, 1[$ with $\gamma > 0$ suff. small. Then,

$$\begin{aligned} \langle e_\gamma, f \rangle_{X' \times X} &= \langle v_\gamma, Af \rangle_{X' \times X} = - \int_0^1 Af(t) d\eta_\gamma(t) \\ &= \frac{Af(z + \gamma) - Af(z - \gamma)}{2\gamma} \xrightarrow{\gamma \rightarrow 0} (Af)'(z) = f(z). \end{aligned}$$

Surrogate kernels from the underlying continuous setting (cont'd)

Having continuous kernels $v_{d,i}$ satisfying

$$|\langle A^* v_{d,i} - e_{d,i}, f \rangle_{X' \times X}| \leq \varepsilon_{d,i} \|f\|_X, \quad i = 1, \dots, d,$$

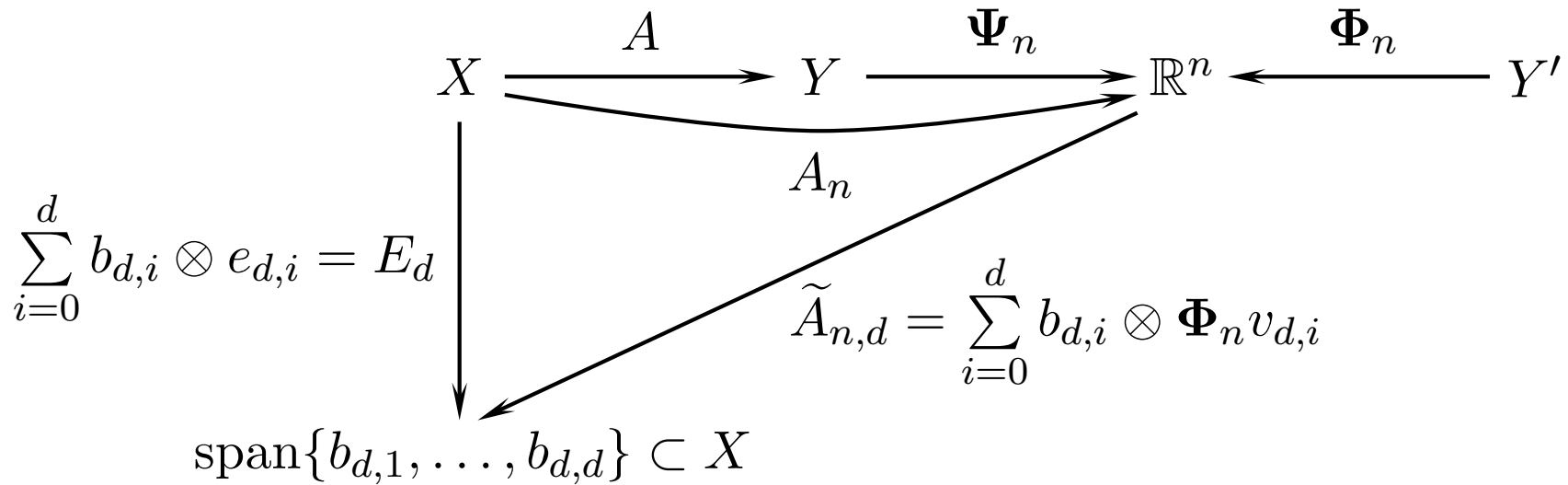
at our disposal we define the approximate inverse with **surrogate kernels**

$$\tilde{A}_{n,d} \alpha := \sum_{i=1}^d \langle \Phi_n v_{d,i}, \alpha \rangle_2 b_{d,i}.$$

Here, $\Phi_n : Y' \rightarrow \mathbb{R}^n$ is linear and continuous and needs to be defined such that

$$\lim_{\substack{n \rightarrow \infty \\ d \rightarrow \infty}} \|\tilde{A}_{n,d} A_n f - f\|_X = 0 \quad \text{for any } f \in X.$$

Interlude: overview of the involved operators



$$E_d \approx \tilde{A}_{n,d} A_n$$

Convergence

Theorem: If all building blocks are chosen adequately then

$$\|\tilde{A}_{n,d}A_n f - f\|_X \lesssim \|f - E_d f\|_X + \sigma(d) \left(\rho_n \max_{1 \leq i \leq d} \|v_{d,i}\|_{Y'} + \max_{1 \leq i \leq d} \varepsilon_{d,i} \right)$$

where $\rho_n \rightarrow 0$ as $n \rightarrow \infty$.

Four error components:

1. Discretization error in X by mollification operator,
2. Discretization error in Y by observation operator and
3. Error due to the surrogate kernels: $\rho_n = \rho_n(Af, \Psi_n, \Phi_n)$,
4. Accuracy of the continuous kernels ($A^*v_{d,i} \approx e_{d,i}$).

$$\left\| \sum_{i=1}^d \alpha_i b_{d,i} \right\|_X \leq \sigma(d) \max_{1 \leq i \leq d} |\alpha_i|, \quad \alpha \in \mathbb{R}^d$$

Convergence (cont'd)

Corollary: Choosing $d = d(n) = d(n, f)$ such that $d(n) \rightarrow \infty$ as $n \rightarrow \infty$ as well as

$$\sigma(d(n)) \rho_n \max_{1 \leq i \leq d(n)} \|v_{d(n),i}\|_{Y'} \rightarrow 0 \quad \text{as } n \rightarrow \infty$$

and

$$\sigma(d(n)) \max_{1 \leq i \leq d(n)} \varepsilon_{d(n),i} \rightarrow 0 \quad \text{as } n \rightarrow \infty$$

we have the convergence

$$\lim_{n \rightarrow \infty} \|\tilde{A}_{n,d(n)} A_n f - f\|_X = 0.$$

Regularization property

The noise model:

$$(\Psi_n^\delta y)_k = (\Psi_n y)_k + \delta_k, \quad |\delta_k| \leq \delta, \quad y \in Y, \quad (2)$$

where $\delta > 0$ is the noise level.

Theorem: Adopt all previous assumptions.

Let $d = d(n) = d(n, f) \rightarrow \infty$ as $n \rightarrow \infty$ such that convergence holds in the noise-free setting.

If $n = n_\delta$ such that $n_\delta \rightarrow \infty$ when $\delta \rightarrow 0$ as well as

$$\delta \sigma(d(n_\delta)) \sqrt{n_\delta} \max_{1 \leq i \leq d(n_\delta)} \|\Phi_{n_\delta} v_{d(n_\delta), i}\|_2 \rightarrow 0 \quad \text{as } \delta \rightarrow 0$$

then

$$\lim_{\delta \rightarrow 0} \sup \left\{ \|\tilde{A}_{n_\delta, d(n_\delta)} \Psi_{n_\delta}^\delta A f - f\|_X : \Psi_{n_\delta}^\delta \text{ fulfills (2)} \right\} = 0.$$

Example: the integration operator

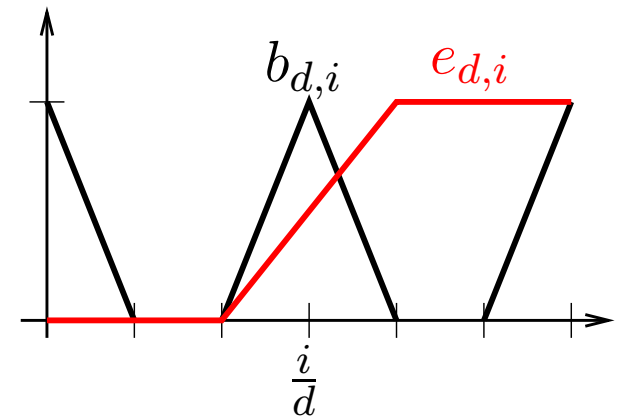
► $X = (\mathcal{C}([0, 1]), \|\cdot\|_\infty)$, $A: X \rightarrow X$, $Af(x) = \int_0^x f(t)dt$

► Let $\psi_{n,0} = \chi_{]0,1]}$ and $\psi_{n,k} = \chi_{[k/n,1]}$, $k = 1, \dots, n$. Then,

$$\psi_{n,k} \in X' \quad \text{and} \quad (\Psi_n g)_k = \langle \psi_{n,k}, g \rangle_{X' \times X} = g\left(\frac{k}{n}\right).$$

► $A_n: X \rightarrow \mathbb{R}^n$, $(A_n f)_k = \int_0^{\frac{k}{n}} f(t)dt$, $k = 0, \dots, n$.

► $\tilde{A}_{n,d} w = \sum_{i=0}^d \langle \Phi_n v_{d,i}, w \rangle_2 b_{d,i}$, $v_{d,i} = -e'_{d,i}$,

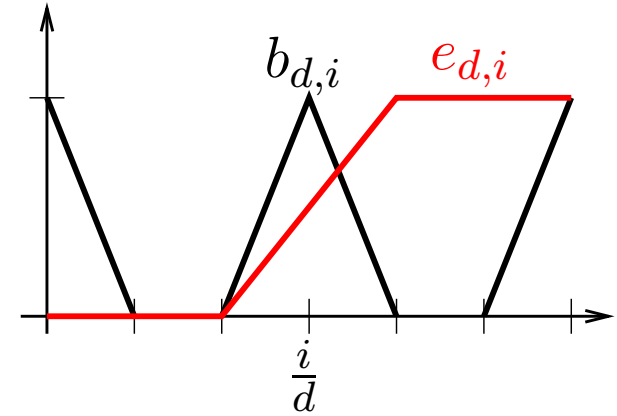


► $\Phi_n: Y' \rightarrow \mathbb{R}^{n+1}$ is given by

$$(\Phi_n v)_k = \langle v, b_{n,k} \rangle_{X' \times X}$$

Example: the integration operator (cont'd)

$$\tilde{A}_{n,d}w = \sum_{i=0}^d \langle \Phi_n v_{d,i}, w \rangle_2 b_{d,i}, \quad v_{d,i} = -e'_{d,i}$$



If $n = d$ then $\langle \Phi_n v_{d,i}, w \rangle_2$ is easily evaluated to be

$$\tilde{A}_{n,n}w\left(\frac{k}{n}\right) = \langle \Phi_n v_{n,k}, w \rangle_2 = n \begin{cases} w_1 - w_0 & : k = 0, \\ (w_{k+1} - w_{k-1})/2 & : k = 1, \dots, n-1, \\ w_n - w_{n-1} & : k = n. \end{cases}$$

Compare with the continuous setting

$$\langle v_{n,k}, Af \rangle_{X' \times X} = \frac{Af\left(\frac{k+1}{n}\right) - Af\left(\frac{k-1}{n}\right)}{\frac{2}{n}}.$$

Example: the integration operator (cont'd)

We have that

$$\|\tilde{A}_{n,d}A_n f - f\|_\infty \lesssim \|f - E_d f\|_\infty + \underbrace{\sigma(d)}_{=1} \left(\underbrace{\lesssim n^{-1}}_{\rho_n} \underbrace{\max_{1 \leq i \leq d} \|v_{d,i}\|_{X'}}_{\sim d} + \underbrace{\max_{1 \leq i \leq d} \varepsilon_{d,i}}_{=0} \right)$$

Setting $d(n) = n^{1-\gamma}$ for one $0 < \gamma < 1$ yields

$$\lim_{n \rightarrow \infty} \|f - \tilde{A}_{n,d(n)}A_n f\|_\infty = 0 \quad \text{for any } f \in \mathcal{C}(0,1).$$

Consequence

We can recover about n moments of f from n observations of Af .

Remark

In a comparable Hilbert space setting we can only recover about $n^{2/3}$ moments from n observations.

Example: the integration operator (cont'd)

$$(\Psi_n^\delta g)_k = g\left(\frac{k}{n}\right) + \delta_k, \quad |\delta_k| \leq \delta \quad (3)$$

Data error: $\delta \sqrt{n} \max_{1 \leq i \leq d(n)} \|\Phi_n v_{d(n),i}\|_2 \sim \delta \sqrt{n} d$

Setting $d(n) = n^{1-\gamma}$, $0 < \gamma < 1$, and $n_\delta \sim \delta^{\frac{\gamma-1}{3/2-\gamma}}$ yields

$$\lim_{\delta \rightarrow 0} \sup \left\{ \|\tilde{A}_{n_\delta, d(n_\delta)} \Psi_{n_\delta}^\delta A f - f\|_\infty : \Psi_{n_\delta}^\delta \text{ fulfills (3)} \right\} = 0.$$

What you should recall from this talk

Approximate Inverse

- requires no geometric assumptions on Banach spaces and
- discretization effects are included into the analysis.



Th. Schuster, A. Rieder, F. Schöpfer

The approximate inverse in action IV: semi-discrete equations in a Banach space setting

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