

A3 Christoffelsymbole von Graphen

Sei $f: U \subset \mathbb{R}^2 \rightarrow \mathbb{R}$ eine differenzierbare Funktion.

Wir bestimmen die Christoffelsymbole der parametrisierten Flächen:

$$x: U \rightarrow \mathbb{R}^3; (u_1, u_2) \mapsto (u_1, u_2, f(u_1, u_2))$$

Beispiele: siehe A1 a), b) Blatt 13: Ellipsoides u. hyperbolisches Paraboloid.

$$x_{u_1} = (1, 0, f_{u_1}) \quad ; \quad x_{u_2} = (0, 1, f_{u_2})$$

$$g_{11} = 1 + f_{u_1}^2 \quad ; \quad g_{22} = 1 + f_{u_2}^2 \quad ; \quad g_{12} = g_{21} = f_{u_1} f_{u_2}$$

$$\Rightarrow g = 1 + f_{u_1}^2 + f_{u_2}^2$$

$$\text{und: } g_{11,1} = 2 f_{u_1} f_{u_1 u_1} \quad ; \quad g_{22,2} = 2 f_{u_2} f_{u_2 u_2}$$

$$g_{12,1} = g_{21,1} = f_{u_1 u_1} f_{u_2} + f_{u_1} f_{u_1 u_2}$$

$$g_{12,2} = g_{21,2} = f_{u_1 u_2} f_{u_1} + f_{u_2} f_{u_1 u_2}$$

$$g_{11,2} = 2 f_{u_1} f_{u_1 u_2} \quad ; \quad g_{22,1} = 2 f_{u_2} f_{u_1 u_2}$$

Sei $(g_{ij}) = \begin{pmatrix} g_{11} & g_{12} \\ g_{21} & g_{22} \end{pmatrix}$. Dann ist die Inverse gegeben durch:

$$(g_{ij})^{-1} = (g^{lk}) = \frac{1}{g} \begin{pmatrix} g_{22} & -g_{12} \\ -g_{21} & g_{11} \end{pmatrix} \quad (\text{Überprüfen!}) \quad \text{Also gilt:}$$

$$g^{11} = \frac{g_{22}}{g} = \frac{1 + f_{u_2}^2}{g} \quad ; \quad g^{22} = \frac{g_{11}}{g} = \frac{1 + f_{u_1}^2}{g} \quad ; \quad g^{12} = g^{21} = \frac{-g_{12}}{g} = \frac{-f_{u_1} f_{u_2}}{g}$$

Die Christoffelsymbole sind gegeben durch:

$$\Gamma_{ik}^l := \frac{1}{2} g^{lj} (g_{j i, k} + g_{j k, i} - g_{i k, j}) \quad ; \quad (\text{über den Index } j \text{ wird summiert, } j=1,2)$$

Wege ~~g_{ij}~~ $g_{mn} = g_{nm}$ gilt: $\Gamma_{ik}^l = \Gamma_{ki}^l$

$$\Gamma_{11}^1 = \underbrace{\frac{1}{2} g^{11} (g_{11,1} + g_{11,1} - g_{11,1})}_{j=1 \text{ - Term}} + \underbrace{\frac{1}{2} g^{12} (g_{12,1} + g_{21,1} - g_{11,2})}_{j=2 \text{ - Term}}$$

$$= \frac{1}{2} \frac{(1+t_{11})}{g} \cdot 2 t_{11} t_{11,1} + \frac{1}{2} \frac{(-t_{12} t_{21})}{g} [2 (t_{11,1} t_{11} + t_{11} t_{11,1}) - 2 t_{11} t_{11,1}]$$

$$= \frac{1}{g} [t_{11} t_{11,1} + \cancel{t_{11} t_{11}^2 t_{11,1}} - \cancel{t_{11} t_{11}^2 t_{11,1}} - \cancel{t_{11} t_{11}^2 t_{11,1}} + \cancel{2 t_{11} t_{11} t_{11,1}}]$$

$$= \frac{t_{11} t_{11,1}}{g} = \frac{t_{11} t_{11,1}}{1+t_{11}^2+t_{12}^2}$$

$$\Gamma_{11}^2 = \underbrace{\frac{1}{2} g^{21} (g_{11,1})}_{j=1 \text{ - Term}} + \underbrace{\frac{1}{2} g^{22} (2 g_{11,2} - g_{11,2})}_{j=2 \text{ - Term}}$$

$$= \frac{1}{g} [-t_{12}^2 t_{11,1} + (1+t_{12}^2) (2 t_{11,2} t_{11} + t_{11} t_{11,2} - t_{11} t_{11,2})]$$

$$= \frac{1}{g} [t_{11,2} t_{11}] = \frac{t_{12} t_{11,2}}{1+t_{11}^2+t_{12}^2}$$

$$\Gamma_{12}^1 = \Gamma_{21}^1 = \underbrace{\frac{1}{2} g^{11} (g_{21,1} + g_{11,2} - g_{21,1})}_{j=1 \text{ - Term}} + \underbrace{\frac{1}{2} g^{12} (g_{11,1} + g_{11,2} - g_{11,2})}_{= 0}$$

$$= \frac{1}{g} [(1+t_{11}) t_{11} t_{11,2} - t_{11} t_{11}^2 t_{11,2}]$$

$$= \frac{t_{11} t_{11,2}}{g} = \frac{t_{11} t_{11,2}}{1+t_{11}^2+t_{12}^2}$$

$$\Gamma_{12}^2 = \Gamma_{21}^2 = \frac{1}{2} g^{21} g_{11,2} + \frac{1}{2} g^{22} g_{11,1} = \frac{1}{g} [-t_{12}^2 t_{11} t_{11,2} + (1+t_{12}^2) t_{11} t_{11,2}]$$

$$= \frac{t_{11} t_{11,2}}{g} = \frac{t_{12} t_{11,2}}{1+t_{11}^2+t_{12}^2}$$

$$\Gamma_{22}^1 = \frac{1}{2} g^{11} (g_{21,2} + g_{12,2} - g_{22,1}) + \frac{1}{2} g^{11} (g_{21,1})$$

$$= \frac{f_{u_1} f_{u_2} u_2}{1 + f_{u_1}^2 + f_{u_2}^2}$$

$$\Gamma_{22}^2 = \frac{1}{2} g^{22} (g_{22,2} + g_{22,2} - g_{22,2}) + \frac{1}{2} g^{22} (g_{22,2})$$

$$= \frac{f_{u_2} f_{u_2} u_2}{1 + f_{u_1}^2 + f_{u_2}^2}$$

Fazit: $\Gamma_{ik}^l = \frac{1}{g} f_{ik} f_l \equiv \frac{1}{g} f_{u_i} u_k f_{u_l}$