

(1a) Assume that the maximum  $u$ 's attained at  $x_0 \in U$ . Then  $u_{x_i}(x_0) = 0$

$$\begin{aligned} \text{So } Lu(x_0) &= - \sum_{i,j=1}^n a^{ij}(x_0) u_{x_i x_j}(x_0) \\ &= - \text{Tr}(A(x_0) \text{Hess}u(x_0)) \end{aligned}$$

where  $A(x_0) = (a^{ij}(x_0))_{i,j=1}^n$ . But since  $L$  is elliptic  $A(x_0)$  is positive definite.

Since  $u$  has maximum at  $x_0$  we

have  $\text{Hess}u(x_0)$  is positive semi-definite. Therefore,

$$\text{Tr}(A(x_0) \text{Hess}u(x_0)) \leq 0 \quad \text{so } Lu(x_0) \geq 0$$

contradiction. Thus the maximum is attained on the boundary.

(1b) Since  $u$  is harmonic its minimum is attained on the boundary  $\partial B_R(0)$ .  
Since  $1 + 5\cos^2\theta \geq 1$  and  $1 + 5\cos^2(\frac{\pi}{2}) = 1$   
the minimum of  $u|_{B_R(0)}$  and therefore

on  $\overline{B_R(0)}$  is 1. The minimum can not be attained on the interior because the function is not constant.

On the boundary the minimum is attained for  $\theta = \frac{\pi}{2}$  and for  $\theta = \frac{3\pi}{2}$ .

So in total the minimum is attained at 2 points.

(1c) By Green's representation formula we have that

$$u(x) = \int_{\Omega} \gamma_n(x-y) (-\Delta u(y)) dy + \int_{\partial\Omega} (\gamma_n(x-y) \nabla u(y) - u(y) \nabla_{\nu} \gamma_n(x-y)) \cdot \nu(y) d\sigma_y. \quad (1)$$

Now since  $G(x,y) = \gamma_n(x-y) + w(x,y)$  and  $w$  is harmonic w.r.t.  $y$  in  $\Omega \forall x \in \bar{\Omega}$  we have:

$$\begin{aligned} \int_{\partial\Omega} w(x-y) \cdot \nabla u(y) - u(y) \nabla_{\nu} w(x-y) d\sigma_y &= \int_{\Omega} \operatorname{div}_y (w(x-y) \cdot \nabla u(y) + u(y) \nabla_{\nu} w(x-y)) dy \\ &= \int_{\Omega} w(x-y) \Delta u(y) dy - \int_{\Omega} u(y) \underbrace{\Delta_y w(x-y)}_{=0} dy \\ &\Rightarrow \int_{\Omega} w(x-y) \Delta u(y) dy + \int_{\partial\Omega} w(x-y) \nabla u(y) - u(y) \nabla_{\nu} w(x-y) d\sigma_y \quad (2) \end{aligned}$$

Adding (1), (2) and using (1) we find.

$$u(x) = \int_{\Omega} G(x,y) (-\Delta u(y)) dy + \int_{\partial\Omega} G(x,y) \nabla u(y) - u(y) \nabla_{\nu} G(x,y) d\sigma_y$$

since  $G(x,y) = 0$  in  $\Omega \times \partial\Omega$  we arrive at the desired formula.

2a) We have that

since  $\int \phi(t, x-y) dy = 1$

$$u(t, x) - f(x) = \int \phi(t, x-y) f(y) dy - \int \phi(t, x-y) f(x) dy$$
$$= \int \phi(t, x-y) (f(y) - f(x)) dy$$

$$= \int \phi(t, y) (f(x-y) - f(x)) dy$$

where we have used that

$$\int \phi(t, y) f(x) dy = f(x) = \int \phi(t, x-y) f(x) dy$$

and that  $\phi(t, \cdot) * f = f * \phi(t, \cdot)$ .

$$\text{So } u(t, x) - f(x) = \int_{t^{1/2}}^{\frac{y}{\sqrt{t}}} \phi(1, \frac{y}{\sqrt{t}}) (f(x-y) - f(x)) dy$$

$$\frac{\tilde{y} = \frac{y}{\sqrt{t}}}{d\tilde{y} = \frac{1}{\sqrt{t}} dy} \int \phi(1, \tilde{y}) (f(x - t\tilde{y}) - f(x)) d\tilde{y}$$

$$\text{Thus } \int |u(t, x) - f(x)| dx = \int \int |\phi(1, \tilde{y})| |f(x - t\tilde{y}) - f(x)| d\tilde{y} dx$$

Tonelli

$$\leq \int |\phi(t, \vec{y})| \underbrace{\int |f(x-t\vec{y}) - f(x)| dx}_{\rightarrow 0 \text{ as } t \rightarrow 0 \text{ pointwise}}$$

↓ due to the hint.

0 as  $t \rightarrow 0$  pointwise.

and  $\phi(t, \vec{y}) \int |f(x-t\vec{y}) - f(x)| dx \leq \underbrace{\phi(t, \vec{y})}_{\in L^1} \underbrace{2\|f\|}_{\in L^1}$

so we can apply dominated convergence theorem to obtain the desired result.

(2b) We illustrate how to solve it if  $u(0, x) = g(x)$ .

$$c^2 u_{xx} \Rightarrow (\partial_t^2 - c^2 \partial_x^2) u = 0 \Rightarrow (\partial_t - c \partial_x) \underbrace{(\partial_t + c \partial_x) u}_v = 0$$

$$\int (\partial_t - c \partial_x) v = 0$$

$$\left. \begin{array}{l} v(0, x) = \partial_t u(0, x) + c \partial_x u(0, x) = h(x) + c g'(x) \end{array} \right\} \underline{(2)}$$

$$v(t, x) = h(x + ct) + g'(x + ct)$$

$$\left\{ \begin{array}{l} (\partial_t + c \partial_x) u(t, x) = h(x + ct) + g'(x + ct) \quad \underline{(2)} \\ u(0, x) = g(x) \end{array} \right.$$

$$u(t, x) = g(x - ct) + \int_0^t [h(x - ct + s) + g'(x - ct + s)] ds$$

$$= g(x - ct) + \int_0^t h(x - ct + 2cs) ds + \int_0^t g'(x - ct + 2cs) ds$$

$$= g(x - ct) + \frac{g(x - ct + 2cs)}{2} \Big|_0^t + \int_0^t h(x - ct + 2cs) ds$$

$$\stackrel{dy = 2c ds}{=} \frac{1}{2c} \int_{x-ct}^{x+ct} h(y) dy$$

3a) (i) The equation has the form

$$\frac{\partial^2 u}{\partial x^2} + \frac{x^2}{2} \frac{\partial^2 u}{\partial x \partial y} + \frac{x^2}{2} \frac{\partial^2 u}{\partial y \partial x} - y \frac{\partial u}{\partial x} = 0$$

the second order terms are

described by the matrix

$$A(x) = \begin{pmatrix} xy & \frac{x^2}{2} \\ \frac{x^2}{2} & 0 \end{pmatrix}. \quad \text{Since } \det A(x) = -\frac{x^4}{4} < 0$$

it follows right away that the e.v. are of opposite sign so the equation is hyperbolic.

$$(ii) \quad \partial^\alpha u = g \Leftrightarrow \int_U u v = (-1)^\alpha \int_U g \partial^\alpha v \quad \forall v \in C_c^\infty(U)$$

$$P(U) = \{u \in L^p(U) : \partial^\alpha u \in L^p(U), \forall |\alpha| \leq 1\}$$

(3b) We have  $\int_{\mathbb{R}^3} \delta_3(x-y) \rho(y) dy =$

$= \int_{B_R(0)} \delta_3(x-y) \rho(y) dy = \int_0^R \rho(t) \underbrace{\int_{\partial B_t(0)} \delta_3(x-y) d\sigma_y}_{\text{due to spherical symmetry}} dt.$

$= \rho(x) |\partial B_t(0)|$  by mean value property since  $|x| > t$  so  $\rho(y) = \delta_3(x-y)$  is harmonic in  $B_t(0)$ .

$= \rho(x) \int_0^R \rho(t) |\partial B_t(0)| dt = \rho(x) \int_{B_R(0)} \rho(y) dy$

$= \rho(x) \int_{\mathbb{R}^3} \rho(y) dy.$



$$(3c) \quad f(x) = e^{-\pi x^2} \Rightarrow f'(x) = -2\pi x e^{-\pi x^2}$$

$$\Rightarrow f'(x) = -2\pi x f(x).$$

$$\text{and } f(0) = 1$$

Since  $f \in S$  so  $x f, f' \in S$  we obtain that

$$\widehat{x f} = -2\pi x \widehat{f} \quad \Rightarrow$$

$$i \widehat{f'}(\xi) = -2\pi i \xi \widehat{f}(\xi) \Rightarrow i(2\pi i \xi) \widehat{f}(\xi) = i \widehat{f'}(\xi)$$

$$\Rightarrow \widehat{f'}(\xi) = -2\pi \xi \widehat{f}(\xi).$$

But  $\widehat{f}(0) = \int e^{-2\pi i x \cdot 0} f(x) dx \stackrel{\text{Hint}}{=} 1.$

So  $\widehat{f}$  solves the same initial

value problem as  $f$  so by uniqueness  $\widehat{f} = f.$

(4d) If we substitute  $u(t,x) = w(t)v(x)$   
in  $u_{tt} = u_{xx}$  we find  $w''(t)v(x) = w(t)v''(x)$

$$\Rightarrow \frac{w''(t)}{w(t)} = \frac{v''(x)}{v(x)} = d \in \mathbb{R}$$

↓  
depends only  
on  $t$

↓  
depends  
only on  $x$

Thus they both  
have to be a  
constant.

So  $\begin{cases} v''(x) = dv(x) \\ v(0) = 0, v(L) = 0 \end{cases} \rightarrow$  from boundary  
conditions.

Case 1  $d > 0$ . Then  $v(x) = C_1 e^{\sqrt{d}x} + C_2 e^{-\sqrt{d}x}$

$$v(0) = 0 \Rightarrow C_1 + C_2 = 0 \Rightarrow C_2 = -C_1$$

$$v(L) = 0 \Rightarrow C_1 e^{\sqrt{d}L} - C_1 e^{-\sqrt{d}L} = 0 \Rightarrow$$

$$C_1 \underbrace{(e^{\sqrt{d}L} - e^{-\sqrt{d}L})}_{\neq 0 \text{ since } d, L > 0} = 0 \Rightarrow C_1 = 0$$

$\neq 0$  since  $d, L > 0$

Therefore  $C_1 = C_2 = 0 \Rightarrow v(x) = 0$

so only trivial solution.

Case 2  $d=0$ . Then  $v''(x)=0 \Rightarrow v(x)=C_1+C_2x$ .

$$v(0)=0 \Rightarrow C_1=0. \quad v(L)=0 \Rightarrow C_2L=0 \Rightarrow C_2=0$$

So  $v=0$ .

Case 3:  $d < 0$ . Then  $v(x) = C_1 \cos(\sqrt{d}x) + C_2 \sin(\sqrt{d}x)$

$$v(0)=0 \Rightarrow C_1=0. \quad \text{So } v(x) = C_2 \sin(\sqrt{d}x).$$

$$v(L)=0 \Rightarrow C_2 \underbrace{\sin(\sqrt{d}L)}_{} = 0.$$

is not zero

only when this is zero.

So nontrivial solution  $\leadsto \sin(\sqrt{d}L)=0$ .

$$\sqrt{d}L = n\pi, \quad n \in \mathbb{N}$$

$$d = -\frac{n^2\pi^2}{L^2}$$

$$\leadsto v_n(x) = \sin\left(\frac{n\pi}{L}x\right).$$

In this case we find  $w_n''(t) = -d_n w_n(t)$ .

$$\leadsto w_n(t) = C_1 \cos\left(\frac{n\pi x}{L}\right) + C_2 \sin\left(\frac{n\pi x}{L}\right) \quad 12:48$$

So we end up with solutions of the form

$$u_n(x,t) = \left( C_1 \cos\left(\frac{n\pi x}{L}\right) + C_2 \sin\left(\frac{n\pi x}{L}\right) \right) \sin\left(\frac{n\pi}{L}x\right), \quad n \in \mathbb{N}.$$

(4b) (i) Let  $(u_n)_{n \in \mathbb{N}} \subset X$  be a minimizing sequence. Then  $\|u_n\|_{W_0^{1,2}(U)}^2 = \|u_n\|^2 + E(u_n)$

= 1 since  $u_n \in X$    
 ↓   
 bounded   
 since  $u_n$  minimizing sequence

So  $\|u_n\|_{W_0^{1,2}(U)}$  is bounded thus

$\exists u_0 \in W_0^{1,2}(U)$  and a subsequence  $u_{n_k}$  of  $u_n$  such that  $u_{n_k} \rightarrow u_0$  in  $W_0^{1,2}(U)$ .

By Rellich Kondrachev it follows that

$$u_{n_k} \rightarrow u_0 \text{ in } L^2(U) \text{ so } \|u_0\|_{L^2} = 1$$

Thus  $u_0 \in X$  On the other hand

$$\|u_0\|_{W_0^{1,2}(U)}^2 \leq \liminf_{k \rightarrow \infty} \|u_{n_k}\|_{W_0^{1,2}(U)}^2 = 1$$

$$\|u_0\|_{L^2(U)} + E(u_0) = \underbrace{\|u_{n_k}\|^2}_{=1} + \liminf_{k \rightarrow \infty} E(u_{n_k})$$

$\Rightarrow E(u_0) \leq \liminf_{k \rightarrow \infty} E(u_{n_k})$  and since  $u_{n_k}$  is minimizing and  $u_0 \in X$  it follows that  $u_0$  is a minimizer

(ii) We used part (i) to prove that there is an orthonormal basis of  $L^2(U)$  consisting of functions  $(u_n)_{n \in \mathbb{N}} \subset W_0^{1,2}(U)$  that are eigenfunctions of the Laplacian.