

*Exercise 30.* By definition  $P_n^{U,\alpha}(\psi)$  is the infimum over  $\eta \in \mathcal{F}_{s,c}(L^2(\mathbb{R}^3))$ ,  $\|\eta\| = 1$  of the expression

$$(1) \quad \sum_{j=1}^n \|\nabla_j \psi\|_2^2 + \left\langle \psi, \sum_{1 \leq i < j \leq n} \frac{U}{|x_i - x_j|} \psi \right\rangle + \left\langle \psi \otimes \eta, \left( \int a^*(k)a(k)dk - c\sqrt{\alpha} \sum_{j=1}^n \int \frac{e^{-ikx_j} a^*(k) + e^{ikx_j} a(k)}{|k|} dk \right) (\psi \otimes \eta) \right\rangle.$$

From the definition of the function  $\rho$  we have

$$\rho(x) = \sum_{j=1}^n \int_{\mathbb{R}^{3(n-1)}} \left| \psi(x_1, \dots, x_{j-1}, x, x_{j+1}, \dots, x_n) \right|^2 dx_1 \dots dx_{j-1} dx_{j+1} \dots dx_n$$

and thus, its Fourier transform is given by

$$\hat{\rho}(k) = \sum_{j=1}^n \int_{\mathbb{R}^{3n}} e^{-ikx} \left| \psi(x_1, \dots, x_{j-1}, x, x_{j+1}, \dots, x_n) \right|^2 dx_1 \dots dx_{j-1} dx_{j+1} \dots dx_n.$$

This allows us to rewrite the last term of (1) as

$$\left\langle \eta, \left( \int a^*(k)a(k)dk - c\sqrt{\alpha} \int \frac{\hat{\rho}(k)a^*(k) + \bar{\hat{\rho}}(k)a(k)}{|k|} dk \right) \eta \right\rangle$$

and then proceed in exactly the same way as it was presented in class. Under the assumption that there is an  $\eta \in \mathcal{F}_{s,c}(L^2(\mathbb{R}^3))$ ,  $\|\eta\| = 1$  with the property

$$(2) \quad \left\langle \eta, \int dk \left( a^*(k) - c\sqrt{\alpha} \frac{\bar{\hat{\rho}}(k)}{|k|} \right) \left( a(k) - c\sqrt{\alpha} \frac{\hat{\rho}(k)}{|k|} \right) \eta \right\rangle = 0$$

we obtain the desired equality for the operator  $P_n^{U,\alpha}$ . □

*Exercise 31.* Since  $U$  and  $\alpha$  are fixed we drop them from the notation. Consider an  $\epsilon > 0$ . We may find  $\phi \in C_c^\infty(\mathbb{R}^{3k})$  and  $\psi \in C_c^\infty(\mathbb{R}^{3(n-k)})$  such that  $\|\phi\|_2 = \|\psi\|_2 = 1$  and

$$(3) \quad P_k(\phi) < \mathcal{E}_k + \frac{\epsilon}{2} \text{ and } P_{n-k}(\psi) < \mathcal{E}_{n-k} + \frac{\epsilon}{2}.$$

Let us denote by  $\psi_h = \psi(\cdot - h)$  for  $h \in \mathbb{R}^{3(n-k)}$  and observe that  $\phi \otimes \psi_h \in C_c^\infty(\mathbb{R}^n)$ ,  $\|\phi \otimes \psi_h\|_2 = 1$ . We claim

$$(4) \quad \lim_{|h| \rightarrow \infty} P_n(\phi \otimes \psi_h) = P_k(\phi) + P_{n-k}(\psi).$$

Indeed,

$$(5) \quad P_n(\phi \otimes \psi_h) = \sum_{j=1}^n \|\nabla_j(\phi \otimes \psi_h)\|_2^2 + \left\langle \phi \otimes \psi_h, \sum_{1 \leq i < j \leq n} \frac{U}{|x_i - x_j|} (\phi \otimes \psi_h) \right\rangle + -D\alpha \int_{\mathbb{R}^3} \int_{\mathbb{R}^3} \frac{\rho_{\phi \otimes \psi_h}(x) \rho_{\phi \otimes \psi_h}(y)}{|x - y|} dx dy$$

where

$$\rho_{\phi \otimes \psi_h}(x) = \sum_{j=1}^n \int_{\mathbb{R}^{3(n-1)}} \left| (\phi \otimes \psi_h)(x_1, \dots, x_{j-1}, x, x_{j+1}, \dots, x_n) \right|^2 dx_1 \dots dx_{j-1} dx_{j+1} \dots dx_n$$

and  $D$  is a constant.

For the first term of the RHS of (5) it is trivial to see that ( $\|\phi\|_2 = \|\psi\|_2 = 1$ )

$$(6) \quad \sum_{j=1}^n \|\nabla_j(\phi \otimes \psi_h)\|_{L^2(\mathbb{R}^{3n})}^2 = \sum_{j=1}^k \|\nabla_j \phi\|_{L^2(\mathbb{R}^{3k})}^2 + \sum_{j=k+1}^n \|\nabla_j \psi_h\|_{L^2(\mathbb{R}^{3(n-k)})}^2 =$$

$$\sum_{j=1}^k \|\nabla_j \phi\|_{L^2(\mathbb{R}^{3k})}^2 + \sum_{j=k+1}^n \|\nabla_j \psi\|_{L^2(\mathbb{R}^{3(n-k)})}^2.$$

For the second term of the RHS of (5) we have

$$(7) \quad \left\langle \phi \otimes \psi_h, \sum_{1 \leq i < j \leq n} \frac{U}{|x_i - x_j|} (\phi \otimes \psi_h) \right\rangle = \left\langle \phi \otimes \psi_h, \sum_{1 \leq i < j \leq k} \frac{U}{|x_i - x_j|} (\phi \otimes \psi_h) \right\rangle +$$

$$\left\langle \phi \otimes \psi_h, \sum_{k+1 \leq i < j \leq n} \frac{U}{|x_i - x_j|} (\phi \otimes \psi_h) \right\rangle + \left\langle \phi \otimes \psi_h, \sum_{\substack{1 \leq i \leq k \\ k+1 \leq j \leq n}} \frac{U}{|x_i - x_j|} (\phi \otimes \psi_h) \right\rangle =$$

$$\left\langle \phi, \sum_{1 \leq i < j \leq k} \frac{U}{|x_i - x_j|} \phi \right\rangle + \left\langle \psi_h, \sum_{k+1 \leq i < j \leq n} \frac{U}{|x_i - x_j|} \psi_h \right\rangle +$$

$$(8) \quad \left\langle \phi \otimes \psi_h, \sum_{\substack{1 \leq i \leq k \\ k+1 \leq j \leq n}} \frac{U}{|x_i - x_j|} (\phi \otimes \psi_h) \right\rangle \rightarrow$$

$$\left\langle \phi, \sum_{1 \leq i < j \leq k} \frac{U}{|x_i - x_j|} \phi \right\rangle + \left\langle \psi, \sum_{k+1 \leq i < j \leq n} \frac{U}{|x_i - x_j|} \psi \right\rangle + 0$$

as  $|h| \rightarrow \infty$ . This is true since we may estimate all the terms  $\frac{1}{|x_i - x_j|}$  in (8) by the expression

$$\frac{1}{\text{dist}(\text{supp}(\phi), \text{supp}(\psi_h))}$$

which goes to 0 if we let  $|h| \rightarrow \infty$ .

For the third term of the RHS of (5) we first have to notice that

$$(9) \quad \rho_{\phi \otimes \psi_h} = \rho_\phi + \rho_{\psi_h}$$

which implies

$$(10) \quad \int_{\mathbb{R}^3} \int_{\mathbb{R}^3} \frac{\rho_{\phi \otimes \psi_h}(x) \rho_{\phi \otimes \psi_h}(y)}{|x - y|} dx dy = \int_{\mathbb{R}^3} \int_{\mathbb{R}^3} \frac{(\rho_\phi(x) + \rho_{\psi_h}(x))(\rho_\phi(y) + \rho_{\psi_h}(y))}{|x - y|} dx dy =$$

$$(11) \quad \int_{\mathbb{R}^3} \int_{\mathbb{R}^3} \frac{\rho_\phi(x)\rho_\phi(y)}{|x-y|} dx dy + \int_{\mathbb{R}^3} \int_{\mathbb{R}^3} \frac{\rho_{\psi_h}(x)\rho_{\psi_h}(y)}{|x-y|} dx dy +$$

$$(12) \quad \int_{\mathbb{R}^3} \int_{\mathbb{R}^3} \frac{\rho_\phi(x)\rho_{\psi_h}(y)}{|x-y|} dx dy + \int_{\mathbb{R}^3} \int_{\mathbb{R}^3} \frac{\rho_{\psi_h}(x)\rho_\phi(y)}{|x-y|} dx dy \longrightarrow \\ \int_{\mathbb{R}^3} \int_{\mathbb{R}^3} \frac{\rho_\phi(x)\rho_\phi(y)}{|x-y|} dx dy + \int_{\mathbb{R}^3} \int_{\mathbb{R}^3} \frac{\rho_\psi(x)\rho_\psi(y)}{|x-y|} dx dy + 0 + 0$$

as  $|h| \rightarrow \infty$ . This is true since we have that  $\text{dist}(\text{supp}(\phi), \text{supp}(\psi_h)) \rightarrow 0$  as  $|h| \rightarrow \infty$ .

Putting everything together implies (4). From (4) we have

$$\mathcal{E}_n \leq \lim_{|h| \rightarrow \infty} P_n(\phi \otimes \psi_h) = P_k(\phi) + P_{n-k}(\psi) < \mathcal{E}_k + \mathcal{E}_{n-k} + \epsilon$$

and since this holds for all  $\epsilon > 0$  the desired estimate follows. □