

**Nonlinear Boundary Value Problems:
3rd problem sheet**

Exercise 8

Consider the following nonlinear boundary value problem on a bounded domain Ω

$$A(u, v) := \int_{\Omega} [a(\nabla u) \cdot \nabla v + \beta \sum_{i=1}^n b_i(u)(\partial_i u)v + c(u)v] dx = \int_{\Omega} f v dx \quad \forall v \in H_0^1(\Omega)$$

where $f \in L^2(\Omega)$, $\beta \in \mathbb{R}$ and

- i) a is a monotone vectorfield satisfying the conditions i)-iii) from the lecture,
- ii) $b_1, \dots, b_n : \mathbb{R} \rightarrow \mathbb{R}$ are bounded and continuous,
- iii) $c : \mathbb{R} \rightarrow \mathbb{R}$ is continuous and the function $z \mapsto c(z)z$ is bounded from below.

Prove that for small enough $|\beta|$ the following coercivity condition holds:

$$A(u, u) \geq \delta_0 \|u\|_{H_0^1(\Omega)}^2 - \mu_0 \quad \forall u \in H_0^1(\Omega)$$

for some $\delta_0 > 0$, $\mu_0 \in \mathbb{R}$.

Exercise 9

Let the assumptions on a, b_1, \dots, b_n, c from exercise 8 hold. Generalise the Galerkin method from the lecture to prove existence of a solution $u \in H_0^1(\Omega)$ of the boundary value problem

$$\int_{\Omega} [a(\nabla u) \cdot \nabla v + \beta \sum_{i=1}^n b_i(u)(\partial_i u)v + c(u)v] dx = \int_{\Omega} f v dx \quad \forall v \in H_0^1(\Omega)$$

given in exercise 8 provided $|\beta|$ is sufficiently small. You may argue along the followings lines:

1. Prove existence of a Galerkin approximation $u_k \in V_k = \text{span}\{w_1, \dots, w_k\}$ where $\{w_1, w_2, \dots\}$ is an orthonormal basis of $H_0^1(\Omega)$.
2. Use the estimate of exercise 8 to show that the sequence (u_k) has a weakly convergent subsequence.
3. Show that the weak limit $u \in H_0^1(\Omega)$ is a solution of the above problem. To this end use the hints given below to prove that there is a $\xi \in L^2(\Omega)^n$ and a subsequence $(v_j) := (u_{k_j})$ of (u_k) which satisfies:
 - i) $\int_{\Omega} a(\nabla v_j) \cdot \nabla \phi \, dx \rightarrow \int_{\Omega} \xi \cdot \nabla \phi \, dx$ for all $\phi \in H_0^1(\Omega)$.
 - ii) $\int_{\Omega} [\xi \cdot \nabla \phi + \beta \sum_{i=1}^n b_i(u)(\partial_i u)\phi + c(u)\phi] \, dx = \int_{\Omega} f\phi \, dx$ for all $\phi \in H_0^1(\Omega)$.
 - iii) $\int_{\Omega} a(\nabla v_j) \cdot \nabla v_j \, dx \rightarrow \int_{\Omega} \xi \cdot \nabla u \, dx$.
 - iv) $\int_{\Omega} (\xi - a(\nabla \phi)) \cdot (\nabla u - \nabla \phi) \, dx \geq 0$ for all $\phi \in H_0^1(\Omega)$.

Hints:

1. $H_0^1(\Omega)$ imbeds compactly into $L^2(\Omega)$. In particular if $u_k \rightharpoonup u$ then there is a subsequence (u_{k_j}) of (u_k) such that $u_{k_j} \rightarrow u$ in $L^2(\Omega)$.
2. If $g_k \rightarrow g$ in $L^p(\Omega)$ then there is a subsequence (g_{k_j}) and a function $G \in L^p(\Omega)$ such that $g_{k_j} \rightarrow g$ pointwise almost everywhere and $|g_{k_j}| \leq G$.