

(61)

Define  $\mathcal{M} := \rho + \frac{1}{\mu} \text{curl } \xi \in H(\text{curl})$

$\Rightarrow \begin{pmatrix} \xi \\ \mathcal{M} \end{pmatrix} \in \mathcal{D}(M)$ .

Same arguments  $\Rightarrow \text{rg}(I-M)$  dense in  $X \Rightarrow (a)$

3. Now let  $\begin{pmatrix} f \\ g \end{pmatrix} \in X_0$  (instead of  $X$ )

$$0 = \text{div}(\varepsilon f) \stackrel{(14a)}{=} \text{div}(\varepsilon \xi) + \underbrace{\text{div curl } \mathcal{M}}_{=0 \text{ (distributional)}}$$

$$0 = \text{div}(\mu g) \stackrel{(14b)}{=} \text{div}(\mu \mathcal{M}) - \underbrace{\text{div curl } \xi}_{=0 \text{ (distributional)}}$$

$$\left. \begin{array}{l} \\ \\ \end{array} \right\} \Rightarrow \begin{pmatrix} \xi \\ \mathcal{M} \end{pmatrix} \in \mathcal{D}(M) \cap X_0 = \mathcal{D}(M_0)$$

Step 2  $\Rightarrow M$  skew-adjoint in  $X_0$  (b)

(62)

Prove (c): ~~if~~

$$\begin{pmatrix} \xi \\ \mathcal{M} \end{pmatrix} \in \mathcal{D}(M), \quad \begin{pmatrix} \tilde{F}_1 \\ \tilde{F}_2 \end{pmatrix} := M \begin{pmatrix} \xi \\ \mathcal{M} \end{pmatrix} = \begin{pmatrix} \frac{1}{\varepsilon} \text{curl } \mathcal{M} \\ -\frac{1}{\mu} \text{curl } \xi \end{pmatrix}$$

then

$$\left. \begin{array}{l} \text{div}(\varepsilon \tilde{F}_1) = \text{div curl } \mathcal{M} = 0 \\ \text{div}(\mu \tilde{F}_2) = -\text{div curl } \xi = 0 \\ \text{(distributional sense)} \end{array} \right\} \Rightarrow \begin{pmatrix} \tilde{F}_1 \\ \tilde{F}_2 \end{pmatrix} \in X_0 \Rightarrow (c) \quad \blacksquare$$

Remarks:

1. Well-posedness of Maxwell's equations (8) - (10) on a bounded Lipschitz domain  $\Omega \subseteq \mathbb{R}^3$  and boundary conditions

$$\begin{aligned}\Sigma(t) \times \nu &= 0 & t \in \mathbb{R}, x \in \partial\Omega \\ \mu \nabla \times \Sigma(t) \cdot \nu &= 0 & \nu \text{ outer unit normal vector}\end{aligned}$$

can be shown in a similar way.

Additional difficulty: Interpretation of the boundary conditions (trace operators), modified integration by parts formulas (11), (12).

2. Well-posedness of Maxwell's equations with nonzero current density  $J$  and nonzero charge density  $g$  (cf. 1.3) can be discussed via the variation-of-constants formula:

If  $u \in D(A)$  and  $f$  is sufficiently regular, then the classical solution

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of the inhomogeneous ACP

$$\begin{aligned}u'(t) &= Au(t) + f(t) & t \geq 0 \\ u(0) &= u_0\end{aligned}$$

is given by

$$u(t) = T(t)u_0 + \int_0^t T(t-s)f(s) ds.$$

## 2. The Yee scheme

### 2.1 Finite difference method for the wave equation

Consider the wave equation on  $\Omega := (0, 2\pi)$  with periodic boundary conditions:

$$(1) \begin{cases} \partial_t^2 u(t, x) = c^2 \partial_x^2 u(t, x) & t \geq 0, x \in \Omega & \text{PDE} \\ u(t, 0) = u(t, 2\pi) & t \geq 0 & \text{boundary cond.} \\ u(0, x) = u_0(x) & x \in \Omega & \text{initial conditions} \\ \partial_t u(0, x) = v_0(x) & & \end{cases}$$

Assume that  $u_0(0) = u_0(2\pi)$

Assume that a sufficiently smooth classical solution exists.

Equivalent formulation as a first-order problem in time:

$$(2) \begin{cases} \partial_t u(t, x) = v(t, x) & t \geq 0, x \in \Omega \\ \partial_t v(t, x) = c^2 \partial_x^2 u(t, x) \\ u(t, 0) = u(t, 2\pi) \\ u(0, x) = u_0(x) \\ v(0, x) = v_0(x) \end{cases}$$

~~Apply finite difference method~~ ~~Choose  $m \in \mathbb{N}$ , define mesh width  $h := \frac{2\pi}{m}$ , let  $x_j := jh$  for  $j = 0, \dots, m$~~  (mesh width)

~~Choose step-size  $\tau > 0$ , let  $t_n = n\tau$  for  $n = 0, 1, 2, \dots$~~

Choose  $m \in \mathbb{N}$ , define mesh width  $h := \frac{2\pi}{m}$ , let  $x_j := jh$  for  $j = 0, \dots, m$

Choose step-size  $\tau > 0$ , let  $t_n = n\tau$  for  $n = 0, 1, 2, \dots$

Goal: Compute approximations  $u_j^n \approx u(t_n, x_j)$

Approximate derivatives by difference quotients:

$$\partial_t^2 u(t_n, x_j) \approx \frac{u(t_{n+\tau}, x_j) - 2u(t_n, x_j) + u(t_{n-\tau}, x_j))}{\tau^2}$$

$$\partial_x^2 u(t_n, x_j) \approx \frac{u(t_n, x_{j+1}) - 2u(t_n, x_j) + u(t_n, x_{j-1}))}{h^2}$$

This motivates the following finite difference scheme:

$$(3) \quad \frac{u_j^{n+1} - 2u_j^n + u_j^{n-1}}{\tau^2} = c^2 \frac{u_{j+1}^n - 2u_j^n + u_{j-1}^n}{h^2} \quad \begin{matrix} n=1, 2, \dots \\ j=1, \dots, m-1 \\ u_0^n = u_m^n \end{matrix}$$

Initial data:  $u_j^0 = u_0(x_j)$

Define

$$u^n := \begin{pmatrix} u_1^n \\ \vdots \\ u_m^n \end{pmatrix} \in \mathbb{R}^m, \quad A := \frac{1}{h^2} \begin{pmatrix} -2 & 1 & & & 1 \\ & 1 & & & \\ & & \ddots & & \\ & & & 1 & \\ 1 & & & & -2 \end{pmatrix}$$

Then, (3) is equivalent to

$$(4) \quad u^{n+1} - 2u^n + u^{n-1} = \tau^2 c^2 A u^n \quad n=1, 2, \dots$$

This is an explicit two-step method:  $u^n, u^{n-1} \rightarrow u^{n+1}$

The first approximation  $u^1$  is obtained by a starting step:

$$u^1 := u^0 + \tau v^0 + \frac{\tau^2 c^2}{2} A u^0, \quad v^0 := \begin{pmatrix} v_0(x_1) \\ \vdots \\ v_0(x_m) \end{pmatrix}$$

Equivalent one-step formulation:

$$(5) \quad \begin{cases} v^{n+1/2} = v^n + \frac{\tau}{2} c^2 A u^n \\ u^{n+1} = u^n + \tau v^{n+1/2} \\ v^{n+1} = v^{n+1/2} + \frac{\tau}{2} c^2 A u^{n+1} \end{cases}$$

$$v^n \approx \begin{pmatrix} v(t_n, x_1) \\ \vdots \\ v(t_n, x_m) \end{pmatrix}, \quad \text{cf. (2)}$$

## (a) Stability

(3) /  
Observation: The scheme (4) / (5) yields unbounded approximations if the step-size  $\tau$  is too large. Instability!

Which condition must be fulfilled to obtain a bounded numerical solution?

Ansatz: Fourier transform

For every vector  $u^n \in \mathbb{R}^m$ , there is a unique representation

$$u_j^n = \sum_{k=1}^m e^{ikx_j} \hat{u}_k^n \quad (\hat{u}_k^n \in \mathbb{R})$$

Substitute into (3):

$$\begin{aligned} \frac{1}{\tau^2} (u_j^{n+1} - 2u_j^n + u_j^{n-1}) &= \sum_{k=1}^m e^{ikx_j} \frac{1}{\tau^2} (\hat{u}_k^{n+1} - 2\hat{u}_k^n + \hat{u}_k^{n-1}) \\ \stackrel{(3)}{=} \frac{c^2}{h^2} (u_{j+1}^n - 2u_j^n + u_{j-1}^n) &= \frac{c^2}{h^2} \sum_{k=1}^m e^{ikx_j} \hat{u}_k^n (e^{ikh} - 2 + e^{-ikh}) \end{aligned}$$

Compare coefficients:

$$\begin{aligned} \hat{u}_k^{n+1} - 2\hat{u}_k^n + \hat{u}_k^{n-1} &= \left(\frac{c\tau}{h}\right)^2 \hat{u}_k^n \underbrace{(e^{ikh} - 2 + e^{-ikh})}_{= 2(\cos(kh) - 1)} \\ &= 2(\cos(kh) - 1) \end{aligned}$$

Advantage: Decoupling with respect to  $k$ .

Equivalent formulation:

$$\begin{pmatrix} \hat{u}_k^{n+1} \\ \hat{u}_k^n \end{pmatrix} = \begin{pmatrix} 2\alpha & -1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} \hat{u}_k^n \\ \hat{u}_k^{n-1} \end{pmatrix} \quad \alpha := \left(\frac{c\tau}{h}\right)^2 (\cos(kh) - 1)$$

The ~~the~~  $\hat{u}_k^n$  and hence the  $u_j^n$  stay bounded for all  $n$  if and only if the eigenvalues  $\lambda$  of  $\begin{pmatrix} 2\alpha & -1 \\ 1 & 0 \end{pmatrix}$  satisfy  $|\lambda| \leq 1$ .

$$\lambda = \alpha \pm \sqrt{\alpha^2 - 1}$$