

# Time-delayed backward stochastic differential equations: the theory and applications

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The backward stochastic differential equation:

$$Y(t) = \xi + \int_t^T f(s, Y(s), Z(s))ds - \int_t^T Z(s)dW(s), \quad 0 \leq t \leq T.$$

- ▶ A solution is a pair  $(Y, Z)$ .
- ▶ The terminal condition  $\xi$  is an exogenous random variable,
- ▶ The generator  $f$  at time  $s \in [0, T]$  depends on the current value of the solution and an additional source of randomness.



# Time-delayed BSDEs

The time-delayed backward stochastic differential equation:

$$Y(t) = \xi(Y_T, Z_T) + \int_t^T f(s, Y_s, Z_s) ds - \int_t^T Z(s) dW(s), \quad 0 \leq t \leq T.$$

- ▶ The terminal condition  $\xi$  and the generator  $f$  depend on the past values of the solution

$$Y_s := (Y(s+u))_{-T \leq u \leq 0}, \quad Z_s := (Z(s+u))_{-T \leq u \leq 0}.$$

# Time-delayed BSDEs

- ▶ Existence and uniqueness of a solution,
  - ▶ Linear time-delayed BSDEs,
  - ▶ Properties of the solutions.
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- ▶ Applications to portfolio management,
  - ▶ Applications to pricing, hedging of insurance and financial contracts,
  - ▶ Applications to pricing principles and recursive utilities.

# The existence and uniqueness of a solution

# Existence and uniqueness

- (A1) The generator and the terminal condition are product measurable,  $\mathbb{F}$ -adapted and **Lipschitz continuous**, in the sense that for a probability measure  $\alpha$  on  $[-T, 0] \times \mathcal{B}([-T, 0])$  and with constants  $K_1, K_2$  we have:

$$\begin{aligned} & \mathbb{E} \left[ |f(\omega, t, Y_t, Z_t) - f(\omega, t, \tilde{Y}_t, \tilde{Z}_t)|^2 \right] \\ & \leq K_1 \mathbb{E} \left[ \sup_{0 \leq u \leq t} |Y(u) - \tilde{Y}(u)|^2 + \int_{-T}^0 |Z(t+u) - \tilde{Z}(t+u)|^2 \alpha(du) \right], \end{aligned}$$

and

$$\begin{aligned} & \mathbb{E} [ |\xi(\omega, Y_T, Z_T) - \xi(\omega, \tilde{Y}_T, \tilde{Z}_T)|^2 ] \\ & \leq K_2 \mathbb{E} \left[ \sup_{0 \leq u \leq T} |Y(u) - \tilde{Y}(u)|^2 + \int_0^T |Z(u) - \tilde{Z}(u)|^2 du \right], \end{aligned}$$

for any square integrable processes  $(Y, Z), (\tilde{Y}, \tilde{Z})$ ,

# Existence and uniqueness

$$(A2) \quad \mathbb{E} \left[ \int_0^T |f(\omega, t, 0, 0, 0)|^2 dt \right] < \infty,$$

$$(A3) \quad \mathbb{E} [ |\xi(\omega, 0, 0, 0)|^2 ] < \infty,$$

$$(A4) \quad f(\omega, t, \cdot, \cdot) = 0 \text{ for } \omega \in \Omega \text{ and } t < 0.$$



# The result on existence and uniqueness

## Theorem

Assume that **(A1)**-**(A4)** hold. For a sufficiently small time horizon  $T$  or for a sufficiently small Lipschitz constant  $K_1$ , and for a sufficiently small Lipschitz constant  $K_2$ , the time-delayed backward stochastic differential equation has a unique solution.

# Linear time-delayed BSDEs

# Linear time-delayed BSDEs

$$Y(t) = \xi + \int_t^T \int_0^s KY(u)du ds - \int_t^T Z(s)dW(s), \quad 0 \leq t \leq T$$

1.  $K < 0 \Rightarrow$  there exists a unique solution:

$$Y(t) = \mathbb{E}[\xi] \frac{e^{\sqrt{-K}t} + e^{-\sqrt{-K}t}}{e^{\sqrt{-K}T} + e^{-\sqrt{-K}T}} + \frac{1}{2} \int_0^t Z(s) (e^{\sqrt{-K}(t-s)} + e^{-\sqrt{-K}(t-s)}) dW(s),$$

$$Z(t) = \frac{2M(t)}{e^{\sqrt{-K}(T-t)} + e^{-\sqrt{-K}(T-t)}},$$

$$\xi = \mathbb{E}[\xi] + \int_0^T M(t) dW(t).$$

# Linear time-delayed BSDEs

$$Y(t) = \xi + \int_t^T \int_0^s KY(u)du ds - \int_t^T Z(s)dW(s), \quad 0 \leq t \leq T$$

2.  $K > 0$  and  $T\sqrt{K} < \frac{\pi}{2} \Rightarrow$  there exists a unique solution:

$$Y(t) = \mathbb{E}[\xi] \frac{\cos(t\sqrt{K})}{\cos(T\sqrt{K})} + \int_0^t Z(s) \cos((t-s)\sqrt{K})dW(s),$$

$$Z(t) = \frac{M(t)}{\cos((T-t)\sqrt{K})},$$

$$\xi = \mathbb{E}[\xi] + \int_0^T M(t)dW(t).$$

# Linear time-delayed BSDEs

$$Y(t) = \xi + \int_t^T \int_0^s KY(u)du ds - \int_t^T Z(s)dW(s), \quad 0 \leq t \leq T$$

4.  $K > 0$ ,  $T\sqrt{K} = \frac{\pi}{2}$ ,  $\mathbb{E}[\xi] \neq 0 \Rightarrow$  there exists no solution.

## Linear time-delayed BSDEs

$$Y(t) = \xi + \int_t^T \int_0^s KY(u)du ds - \int_t^T Z(s)dW(s), \quad 0 \leq t \leq T$$

$$Z(t) = \frac{M(t)}{\cos((T-t)\sqrt{K})} \mathbf{1}_{\{t > 0\}}, \quad \xi = \mathbb{E}[\xi] + \int_0^T M(t)dW(t).$$

5.  $K > 0$ ,  $T\sqrt{K} = \frac{\pi}{2}$ ,  $\mathbb{E}[\xi] = 0$  and  $\mathbb{E}[\int_0^T |Z(s)|^2 ds] = +\infty \Rightarrow$  there exists no solution.
6.  $K > 0$ ,  $T\sqrt{K} = \frac{\pi}{2}$ ,  $\mathbb{E}[\xi] = 0$  and  $\mathbb{E}[\int_0^T |Z(s)|^2 ds] < \infty \Rightarrow$  there exist multiple solutions:

$$Y(t) = Y(0) \cos(t\sqrt{K}) + \int_0^t Z(s) \cos((t-s)\sqrt{K}) dW(s).$$

# Linear time-delayed BSDEs

$$Y(t) = \xi - \int_t^T \frac{1}{s} \int_0^s \beta Y(u) du ds - \int_t^T Z(s) dW(s), \quad 0 \leq t \leq T$$

- ▶ There exists a unique solution.

The case of  $\beta > 0$ :

$$Y(t) = \mathbb{E}[\xi] \frac{I_0(2\sqrt{\beta t})}{I_0(2\sqrt{\beta T})} + \int_0^t Z(s) \psi(s, t) dW(s),$$

$$Z(t) = \frac{M(t)}{2I_0(2\sqrt{\beta T})\sqrt{\beta t}K_1(2\sqrt{\beta t}) + 2K_0(2\sqrt{\beta T})\sqrt{\beta t}I_1(2\sqrt{\beta t})},$$

$$\psi(s, t) = I_0(2\sqrt{\beta t})K_1(2\sqrt{\beta s}) + K_0(2\sqrt{\beta t})I_1(2\sqrt{\beta s}),$$

$$\xi = \mathbb{E}[\xi] + \int_0^T M(s) dW(s).$$

# Linear time-delayed BSDEs

$$Y(t) = \xi + \int_t^T \int_0^s KZ(u)du ds - \int_t^T Z(s)dW(s), \quad 0 \leq t \leq T$$

- ▶ There exists a unique solution:

$$Y(t) = \mathbb{E}^{\mathbb{Q}}[\xi | \mathcal{F}_t] + (T-t)K \int_0^t Z(s)ds,$$

$$\xi = \mathbb{E}^{\mathbb{Q}}[\xi] + \int_0^T Z(s)dW^{\mathbb{Q}}(s),$$

$$\frac{d\mathbb{Q}}{d\mathbb{P}} \Big|_{\mathcal{F}_T} = \exp \left( K \int_0^T (T-s)dW(s) - K^2 \frac{1}{2} \int_0^T (T-s)^2 ds \right).$$



# Linear time-delayed BSDEs

$$Y(t) = \xi - \int_t^T \frac{1}{s} \int_0^s \beta Z(u) du ds - \int_t^T Z(s) dW(s), \quad 0 \leq t \leq T$$

- ▶ There exists a unique solution:

$$Y(t) = \mathbb{E}^{\mathbb{Q}}[\xi | \mathcal{F}_t] - \beta \ln\left(\frac{T}{t}\right) \int_0^t Z(s) ds,$$

$$\xi = \mathbb{E}^{\mathbb{Q}}[\xi] + \int_0^T Z(s) dW^{\mathbb{Q}}(s),$$

$$\frac{d\mathbb{Q}}{d\mathbb{P}} \Big|_{\mathcal{F}_T} = \exp\left(-\int_0^T \beta \ln\left(\frac{T}{s}\right) dW(s) - \frac{1}{2} \int_0^T \left(\beta \ln\left(\frac{T}{s}\right)\right)^2 ds\right).$$

# Properties of the solutions

# Properties of the solutions

- ▶ A **comparison principle** may not hold, a comparison holds up to a stopping time,
- ▶ If the terminal condition is bounded/non-negative, a solution may be unbounded/negative,
- ▶ A solution exists, but a **measure solution** may not exist, a measure solution exists up to a stopping time,
- ▶ A solution may not be **conditionally invariant** with respect to the terminal condition.

# Malliavin's differentiability

A special case of a BSDE with a time-delayed generator:

$$\begin{aligned} Y(t) = & \xi \\ & + \int_t^T f\left(\omega, s, \int_{-T}^0 Y(s+v)\alpha(dv), \int_{-T}^0 Z(s+v)\alpha(dv)\right) ds \\ & - \int_t^T Z(s)dW(s), \quad 0 \leq t \leq T. \end{aligned}$$

# Malliavin's differentiability

(A5)  $\mathbb{E} \left[ \int_{[0, T]} |D_s \xi|^2 ds \right] < \infty,$

(A6) the mapping  $(y, z, u) \mapsto f(\omega, t, y, z, u)$  is continuously differentiable in  $(y, z, u)$ , with uniformly bounded and continuous partial derivatives  $f_y, f_z, f_u$ ,

(A7) for  $(t, y, z, u) \in [0, T] \times \mathbb{R} \times \mathbb{R} \times \mathbb{R}$  we have that  $f(\cdot, t, y, z, u) \in \mathbb{D}^{1,2}(\mathbb{R})$

$$\mathbb{E} \left[ \int_{[0, T]} \int_0^T |D_s f(\cdot, t, 0, 0, 0)|^2 dt ds \right] < \infty,$$

$$|D_s f(\omega, t, \hat{y}, \hat{z}, ) - D_s f(\omega, t, \tilde{y}, \tilde{z})| \leq K(|\hat{y} - \tilde{y}| + |\hat{z} - \tilde{z}|).$$

# Malliavin's differentiability

## Theorem

Assume that **(A1)-(A7)** hold. *For a sufficiently small time horizon  $T$  or for a sufficiently Lipschitz constant  $K$  there exist unique solutions  $(Y, Z)$  and  $(Y^s, Z^s)$  to the time-delayed BSDEs*

$$\begin{aligned} Y(t) = & \xi \\ & + \int_t^T f\left(\omega, s, \int_{-T}^0 Y(s+v)\alpha(dv), \int_{-T}^0 Z(s+v)\alpha(dv)\right) ds \\ & - \int_t^T Z(s)dW(s), \quad 0 \leq t \leq T, \end{aligned}$$

# Malliavin's differentiability

$$Y^s(t) = D_s \xi + \int_t^T f^s(r, Y_r^s, Z_r^s) dr - \int_t^T Z^s(r) dW(r), \quad 0 \leq s \leq t \leq T,$$

$$\begin{aligned} f^s(r, Y_r^s, Z_r^s) &= D_s f\left(\omega, r, \int_{-T}^0 Y(r+v) \alpha(dv), \int_{-T}^0 Z(r+v) \alpha(dv)\right) \\ &+ f_y\left(\omega, r, \int_{-T}^0 Y(r+v) \alpha(dv), \int_{-T}^0 Z(r+v) \alpha(dv)\right) \\ &\quad \cdot \int_{-T}^0 Y^s(r+v) \alpha(dv) \\ &+ f_z\left(\omega, r, \int_{-T}^0 Y(r+v) \alpha(dv), \int_{-T}^0 Z(r+v) \alpha(dv)\right) \\ &\quad \cdot \int_{-T}^0 Z^s(r+v) \alpha(dv). \end{aligned}$$

# Malliavin's differentiability

- ▶ *The solution  $(Y^s(t), Z^s(t))$  is a version of  $(D_s Y(t), D_s Z(t))$ .*
- ▶ *The process  $(D_t Y(t))^{\mathcal{P}}$  is a version of  $Z(t)$ .*



# Applications to portfolio management, pricing and hedging

# Financial market

The bank account:

$$\frac{dB(t)}{B(t)} = r(t)dt, \quad 0 \leq t \leq T,$$

$$dr(t) = a(t)dt + b(t)dW(t), \quad 0 \leq t \leq T, \quad r(0) = r_0.$$

The bond:

$$\frac{dD(t)}{D(t)} = \mu(t)dt + \sigma(t)dW(t), \quad 0 \leq t \leq T.$$

# The wealth process

The portfolio process:

$$dX(t) = \pi(t)(\mu(t)dt + \sigma(t)dW(t)) + (X(t) - \pi(t))r(t)dt, \quad 0 \leq t \leq T.$$

The terminal liability:

$$X(T) = \xi.$$

The discounted portfolio process:

$$dY(t) = Z(t)dW^{\mathbb{Q}}(t), \quad 0 \leq t \leq T.$$

The discounted terminal liability:

$$Y(T) = \tilde{\xi}.$$

# Hedging problems

- ▶ Common financial instruments: European and Asian options, swaps, swaptions, puts on bonds, caps/floors,
- ▶  $\xi = (L(T_0, T) - K)^+$ ,  $\xi = (D(T_0, T) - K)^+$ ,

$$Y(t) = \tilde{\xi}(W_T) - \int_t^T Z(s) dW^{\mathbb{Q}}(s), \quad 0 \leq t \leq T.$$

- ▶ The terminal pay-off depends on the investment portfolio process or the applied investment strategy,

$$Y(t) = \tilde{\xi}(W_T, Y_T, Z_T) - \int_t^T Z(s) dW^{\mathbb{Q}}(s), \quad 0 \leq t \leq T.$$

# Option Based Portfolio Insurance

- ▶ Invest  $x$  euros,
- ▶ Protect the initial investment and earn an additional return,
- ▶ Buy a bond paying  $x$  at maturity and a call option on  $\lambda$  units of a "benchmark" process  $S$

$$xD(0) + C(x\lambda S(T) - x) = x,$$

- ▶ But  $\lambda$  units of a "benchmark" process  $S$  and a put option on  $\lambda$  units of a "benchmark" process  $S$

$$xS(0) + P(x - x\lambda S(T)) = x.$$

# Option Based Portfolio Insurance

▶  $\xi = X(T) = X(0) + (\lambda S(T) - X(0))^+,$

$$Y(t) = e^{-\int_0^T r(s) ds} (Y(0) + (Y(0)\lambda S(T) - Y(0))^+) - \int_t^T Z(s) dW^{\mathbb{Q}}(s), \quad 0 \leq t \leq T,$$

- ▶ We expect to find multiple solutions of the time-delayed BSDE.

# The applications of time-delayed BSDEs

- ▶ **Portfolio management problems,**
- ▶ **Participating contracts,**  
*"...the benefits are based on the return on a specified pool of assets held by the insurer..."*  
*"...The best estimate should be based on the current assets held by the undertaking. Future changes of the asset allocation should be taken into account..."*

Solvency II Directive

- ▶ **Variable annuities,**
- ▶ **Asset-liability management problems in insurance.**

# Ratchet option

The liability:

$$\xi = \gamma \max\{X(0)e^{gT}, X(t_1)e^{g(T-t_1)}, \dots, X(t_{n-1})e^{g(T-t_{n-1})}, X(T)\}.$$

The time-delayed BSDE:

$$\begin{aligned} Y(t) = & \gamma \max\{Y(0)e^{-\int_0^T r(s)ds+gT}, Y(t_1)e^{-\int_{t_1}^T r(s)ds+g(T-t_1)}, \dots, \\ & Y(t_{n-1})e^{-\int_{t_{n-1}}^T r(s)ds+g(T-t_{n-1})}, Y(T)\} \\ & - \int_t^T Z(s)dW^{\mathbb{Q}}(s), \quad 0 \leq t \leq T. \end{aligned}$$



# Ratchet option

## Proposition

Let  $\mathcal{B}$  denote the following set

$$\mathcal{B} = \left\{ \omega \in \Omega : \gamma \max \left\{ e^{gT} D(0), e^{g(T-t_1)} D(t_1), \dots, e^{g(T-t_{n-1})} D(t_{n-1}), 1 \right\} > 1 \right\}.$$

1. If  $\mathbb{P}(\mathcal{B}) = 0$ ,  $\gamma e^{gT} D(0) = 1$  then there exist multiple solutions  $(Y, Z)$ , which differ in  $Y(0)$ , of the form

$$\begin{aligned} Y(t) &= \gamma Y(0) e^{gT - \int_0^t r(s) ds} D(t), \quad 0 \leq t \leq T, \\ Y(0) e^{gT - \int_0^T r(s) ds} &= Y(0) + \int_0^T Z(s) dW^{\mathbb{Q}}(s). \end{aligned}$$

# Ratchet option

## Definition

2. If  $\mathbb{P}(\mathcal{B}) = 0, \gamma e^{gT} D(0) < 1, \gamma = 1$  then there exist multiple solutions  $(Y, Z)$ , which differ in  $(Y(0), (\tilde{\eta}(t_{m+1}))_{m=0,1,\dots,n-1})$ , of the form

$$Y(t_0) = Y(0),$$

$$Y(t_m) = \gamma \max_{k=0,1,\dots,m} \left\{ Y(t_k) e^{-\int_{t_k}^{t_m} r(u) du} e^{g(T-t_k)} \right\} D(t_m) \\ + \mathbb{E}^{\mathbb{Q}}[\tilde{\eta}(t_{m+1}) | \mathcal{F}_{t_m}],$$

$$Y(t_{m+1}) = \gamma \max_{k=0,1,\dots,m} \left\{ Y(t_k) e^{-\int_{t_k}^{t_{m+1}} r(u) du} e^{g(T-t_k)} \right\} D(t_{m+1}) \\ + \tilde{\eta}(t_{m+1}) \\ = Y(t_m) + \int_{t_m}^{t_{m+1}} Z(s) dW^{\mathbb{Q}}(s),$$

$$Y(t) = \mathbb{E}^{\mathbb{Q}}[Y(t_{m+1}) | \mathcal{F}_t], \quad t_m \leq t \leq t_{m+1}, \quad m = 0, 1, \dots, n-1$$

# Ratchet option

- ▶ Multi-period Option Based Insurance Portfolio,
- ▶ Semi-static hedging,
- ▶ The solution is derived solely from the time-delayed BSDE.

# Ratchet option

The liability:

$$\xi = \gamma \sup_{s \in [0, T]} \{X(s)e^{g(T-s)}\}.$$

The time-delayed BSDE:

$$Y(t) = \gamma \sup_{0 \leq t \leq T} \{Y(t)e^{-\int_t^T r(s)ds + g(T-t)}\} \\ - \int_t^T Z(s)dW^{\mathbb{Q}}(s), \quad 0 \leq t \leq T.$$

# Ratchet option

## Proposition

Let  $\mathcal{C}$  denote the following set

$$\mathcal{C} = \left\{ \omega \in \Omega : \gamma \sup_{0 \leq t \leq T} \{ e^{g(T-t)} D(t) \} > 1 \right\}.$$

1. If  $\mathbb{P}(\mathcal{C}) = 0, \gamma e^{gT} D(0) = 1$  then there exist multiple solutions  $(Y, Z)$ , which differ in  $Y(0)$ , of the form

$$\begin{aligned} Y(t) &= \gamma Y(0) e^{gT - \int_0^t r(s) ds} D(t), \quad 0 \leq t \leq T, \\ Y(0) e^{gT - \int_0^T r(s) ds} &= Y(0) + \int_0^T Z(s) dW^{\mathbb{Q}}(s). \end{aligned}$$

# Ratchet option

## Proposition

2. If  $\mathbb{P}(\mathcal{C}) = 0$ ,  $\gamma e^{gT} D(0) < 1$ ,  $\gamma = 1$  then there exist multiple solutions  $(X, \pi)$ , which differ in  $(X(0), U)$ , of the form

$$\begin{aligned} X(t) &= X(0) + \int_0^t \pi(s) \frac{dD(s)}{D(s)} + \int_0^t (X(s) - \pi(s)) \frac{dB(s)}{B(s)}, \\ \pi(t) &= \gamma \sup_{0 \leq s \leq t} \{X(s) e^{g(T-s)}\} D(t) \\ &\quad + \frac{U(t)}{S(t)} \left( X(t) - \gamma \sup_{0 \leq s \leq t} \{X(s) e^{g(T-s)}\} D(t) \right) \mathbf{1}\{S(t) > 0\} \end{aligned}$$

with the process  $S$  defined as

$$dS(t) = U(t) \frac{dD(t)}{D(t)} + (S(t) - U(t)) \frac{dB(t)}{B(t)}, \quad S(0) = s > 0.$$

# Return smoothing

The liability:

$$\xi = X(0)\beta S + \gamma \frac{1}{T} \int_0^T e^{\int_s^T r(u)du} X(s) ds.$$

The time-delayed BSDE:

$$Y(t) = \beta Y(0)\tilde{S} + \gamma \frac{1}{T} \int_0^T Y(s) ds - \int_t^T Z(s) dW^{\mathbb{Q}}(s), \quad 0 \leq t \leq T.$$

# Return smoothing

## Proposition

If  $\beta \mathbb{E}^{\mathbb{Q}}[\tilde{S}] + \gamma = 1$  then there exist multiple solutions  $(Y, Z)$ , which differ in  $Y(0)$ , of the form

$$Y(t) = Y(0) + \int_0^t Z(s) dW^{\mathbb{Q}}(s), \quad 0 \leq t \leq T,$$

with the  $\mathbb{F}$ -predictable control

$$Z(t) = \frac{1}{1 - \gamma + \gamma \frac{t}{T}} M(t), \quad 0 \leq t \leq T,$$

and the process  $M$  derived from the martingale representation

$$\beta Y(0) \tilde{S} = \beta Y(0) \mathbb{E}^{\mathbb{Q}}[\tilde{S}] + \int_0^T M(t) dW^{\mathbb{Q}}(t).$$



# Return smoothing

A real-life product from the UK market:

$$\begin{aligned} \xi &= X(0) \left( 1 + \max \left\{ g, \beta \left( \frac{X(1)}{X(0)} - 1 \right) \right\} \right) \\ &\cdot \left( 1 + \max \left\{ g, \frac{\beta}{2} \left( \frac{X(1)}{X(0)} + \frac{X(2)}{X(1)} - 2 \right) \right\} \right) \dots \\ &\cdot \left( 1 + \max \left\{ g, \frac{\beta}{T} \left( \frac{X(1)}{X(0)} + \frac{X(2)}{X(1)} + \dots + \frac{X(T)}{X(T-1)} - T \right) \right\} \right). \end{aligned}$$

# Minimum withdrawal rates

Minimum guaranteed withdrawal benefit with an annuity conversion option:

$$dX(t) = \pi(t)(\mu(t)dt + \sigma(t)dW(t)) + (X(t) - \pi(t))r(t)dt - \gamma \left( \sup_{s \in [0, t]} X(s) \right) dt, \quad 0 \leq t \leq T,$$

$$X(T) = La(T),$$

$$a(T) = \mathbb{E}^{\mathbb{Q}} \left[ \int_T^{\infty} e^{-\int_T^s r(u) du} ds \middle| \mathcal{F}_T \right].$$

# Minimum withdrawal rates

The time-delayed BSDE:

$$Y(t) = L\tilde{a}(T) + \int_t^T \gamma \left( \sup_{u \in [0, s]} \{ Y(u) e^{-\int_u^s r(v) dv} \} \right) ds - \int_t^T Z(s) dW^{\mathbb{Q}}(s), \quad 0 \leq t \leq T.$$

- ▶ For a sufficiently small  $\gamma$  or  $T$  there exists a unique non-zero solution.

# Numerical schemes

- ▶ Picard iterations,
- ▶ Random walk approximations,
- ▶ Forward-backward structure of a solution,
- ▶ Convergence?

# Minimum withdrawal rates

Minimum guaranteed withdrawal benefit with an annuity conversion option:

$$dX(t) = \pi(t)(\mu(t)dt + \sigma(t)dW(t)) + (X(t) - \pi(t))r(t)dt - \gamma \sup_{s \in [0, t]} \{X(s)\}dt,$$

$$X(T) = \gamma \sup_{0 \leq s \leq T} \{X(s)\}a(T).$$

$$a(T) = \mathbb{E}^{\mathbb{Q}} \left[ \int_T^{\infty} e^{-\int_T^s r(u)du} ds \middle| \mathcal{F}_T \right].$$

# Applications to pricing principles and recursive utilities

# Prices and utilities

- ▶ We can model a price or a utility as a solution to a BSDE:

$$dY(t) = g(t, Y(t), Z(t))dt + Z(t)dW(t).$$

- ▶ The generator defines a local (subjective) valuation rule:

$$\begin{aligned}\mathbb{E}[dY(t)|\mathcal{F}_t] &= g(t, Y(t), Z(t))dt, \\ \text{Var}[dY(t)|\mathcal{F}_t] &= Z^2(t)dt.\end{aligned}$$

# A habit process

$$dY(t) = -u(c(t))dt - \beta \int_0^t Y(s)dsdt + Z(t)dW(t)$$

- ▶  $\beta > 0$  an anticipation effect,
- ▶  $\beta < 0$  a disappointment effect.



# Pricing principles

$$Y(t) = \mathbb{E}[e^{-\beta(T-t)}\xi|\mathcal{F}_t]$$

- ▶ The local valuation rule:

$$\mathbb{E}[dY(t)|\mathcal{F}_t] = \beta Y(t) dt,$$

- ▶ The price changes proportionally to the last price (a local expected value principle).

# Pricing principles

- ▶ The price changes proportionally to the average of the past prices,
- ▶ The local valuation rule:

$$\mathbb{E}[dY(t)|\mathcal{F}_t] = \frac{1}{t} \int_0^t \beta Y(s) ds dt,$$

- ▶ A time-delayed BSDE with a generator of a moving average type.

# Pricing principles

The global valuation rule:

$$Y(t) = \phi(t, t, T)V(t) - \int_0^t V(s)\phi'(s, t, T)ds,$$
$$V(t) = \mathbb{E}[\xi | \mathcal{F}_t].$$

# Recursive utilities

A habit process:

$$dY(t) = -u(c(t))dt - \beta \frac{1}{t} \int_0^t Y(s) ds dt + Z(t)dW(t).$$

**Thank you very much**

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